

HB60

Lie-Poisson dynamics

$\mathfrak{g}$: Lie algebra

Poisson structure on $C^\infty(\mathfrak{g}^*)$: $\{f, g\}_{LP}(\mu) = \langle \mu, [df, dg] \rangle$

$\Rightarrow$ Lie-Poisson dynamics for Hamiltonian $h \in C^\infty(\mathfrak{g}^*)$:

$$\dot{\mu} = \text{ad}_{dh(\mu)}^* \mu \quad (*)$$

$$\mathfrak{g}^* \simeq \mathfrak{g} \text{ via biinvariant pairing} \Rightarrow \dot{\mu} = [dh(\mu), \mu]$$

Remark: eq. (*) derived for general finite dim. Lie algebras by Poincaré (1901).

Lie-Poisson integrator

Map $\Phi_h: \mathfrak{g}^* \rightarrow \mathfrak{g}^*$

$$(1) \quad \{f \circ \Phi_h, g \circ \Phi_h\} = \{f, g\} \circ \Phi_h \quad (\text{Poisson map})$$

$$(2) \quad \Phi_h(\mu) \in \text{Orb}_\mu^* = \{ \text{Ad}_g^*(\mu) \mid g \in G \} \quad (\text{co-ad orbit})$$

How to construct them?

Lagrangian coordinates viewpoint (cf. Arnold (1966))

Recall Hamiltonian formulation of classical mechanics

Q : configuration manifold

T^*Q : phase space (w. canonical symplectic structure)

$H \in C^\infty(T^*Q)$: Hamiltonian function

$\Rightarrow$ Hamilton's eq. of motion

$$\begin{cases} \dot{q} = \frac{\partial H}{\partial p} \\ \dot{p} = -\frac{\partial H}{\partial q} \end{cases} \quad (**)$$

Connection between (*) and (**)?

What happens if:

(1) Q is a Lie group G

(2) Hamiltonian invariant under action of G on T^*G :

$$H(\underbrace{g \cdot (q, p)}_{(gq, (g^{-1})^* p)}) = H(q, p) \quad \forall g \in G, (q, p) \in T^*G$$

$\Rightarrow$ Reduction theory: dynamics evolve on

T^*G/G How to work with quotient space?

G Lie group $\Rightarrow TG$ trivial (by left or right translation)

$\Rightarrow T^*G \simeq G \times \mathfrak{g}^*$ via $(q, p) \mapsto (q, \underbrace{q^* p}_{\equiv \mu})$
momentum map $\nearrow$

Action on $G \times \mathfrak{g}^*$: $g \cdot (q, \mu) = (gq, (gq)^*(g^{-1})^* \mu)$
 $= (gq, \mu)$

$\Rightarrow \underline{T^*G/G} \simeq G \times \mathfrak{g}^*/G = G/G \times \mathfrak{g}^* \simeq \underline{\mathfrak{g}^*}$

Co-tangent bundle reduction theory:

T^*G/G admits Poisson structure inherited from T^*G

Projection $T^*G \rightarrow \mathfrak{g}^*$ (momentum map)

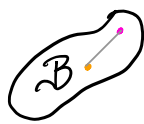
Poisson submersion

In plain words: every LP-system on $\mathfrak{g}^*$ corresponds to canonical Hamiltonian system on T^*G w.r.t G -invariant Hamiltonian
 ... and vice versa

Interpretation by V. Arnold (1966):

Hamiltonian quadratic and pos. def. $\Rightarrow$ integrated curve in G is geodesic
 w.r.t. left (or right) invariant Riemannian metric

Example 1: free rigid body

 body B of infinitesimal mass particles constrained to preserve pairwise lengths $\Rightarrow Q = SO(3)$

Newtonian mechanics $\Rightarrow$ kinetic energy

$$L(R, \dot{R}) = \frac{1}{2} \int_B |\dot{R}x|^2 dx = \frac{1}{2} \int_B |\underbrace{\dot{R}^{-1} \dot{R}}_{\omega \in \mathfrak{so}(3)} x|^2 dx = \omega \cdot \mathbb{I} \omega$$

$\Rightarrow$ LP-system on $\mathfrak{so}(3)^*$:

$\mu = \mathbb{I} \omega$ (Legendre transform)

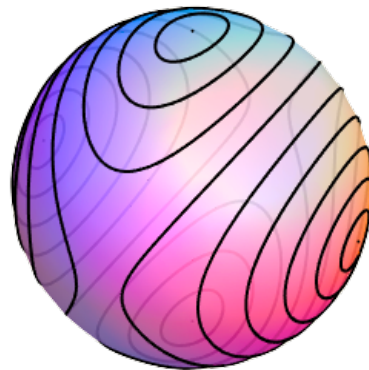
$\mu = \mathbb{I}^{-1} \mu \times \mu$

angular momentum vector

Conservation laws:

(1) total angular momentum $\frac{1}{2} \|\mu\|^2$

(2) energy $\frac{1}{2} \omega \cdot \mu$



moments of inertia

angular velocity vector

Where does conservation of momentum come from?

Weinstein (1983): Poisson manifolds foliated into symplectic leaves:

 each leaf symplectic structure
System evolves on leaf determined by initial condition
 $\Rightarrow$ functions constant on leaves conserved (Casimir functions)

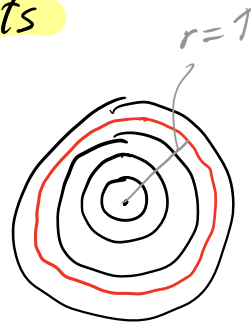
Example 2: point vortices on S^2

leaves for LP-system: co-adjoint orbits

Co-adjoint orbits of $so(3)^* =$ spheres

$\Rightarrow$ LP on $so(3)^* \simeq \mathbb{R}^3$ convenient

way to describe Hamiltonian dynamics on S^2 (and $(S^2)^N$)



$$H: \mathbb{R}^{3N} \rightarrow \mathbb{R}, \quad H(r_1, \dots, r_N) = \frac{1}{4\pi} \sum_{i \neq j} \Gamma_i \Gamma_j \log(1 - r_i \cdot r_j)$$

Dynamics:

$$\dot{r}_i = \frac{1}{2\pi} \sum_{j \neq i} \Gamma_j \frac{r_i \times r_j}{1 - r_i \cdot r_j} \quad (***)$$

Conservation laws:

$\|r_i\|^2$ (Casimirs)

H (Energy)

$J = \sum_{i=1}^N \Gamma_i r_i$ (total angular momentum)

Noether quantity (not Casimir)

Example 3: geodesics on symplectomorphisms

M closed symplectic manifold $\Rightarrow \mathfrak{g} = C^\infty(M)$ Poisson algebra

L^2 -inner product biinvariant: $\langle \{f, g\}, h \rangle_{L^2} = \langle f, \{g, h\} \rangle_{L^2}$

Hamiltonian $H(\omega) = \frac{1}{2} \int_M \omega \Delta^{-1} \omega$

$\Rightarrow$ LP on $\mathfrak{g}^* \simeq C^\infty(M)$: $\dot{\omega} = \{\psi, \omega\}$, $\Delta \psi = \omega$ (****)

Special case: $M = S^2 \Rightarrow$ vorticity formulation of Euler eq. on S^2

Casimirs: $C_f(\omega) = \int_M f(\omega(x)) dx$ $f: \mathbb{R} \rightarrow \mathbb{R}$

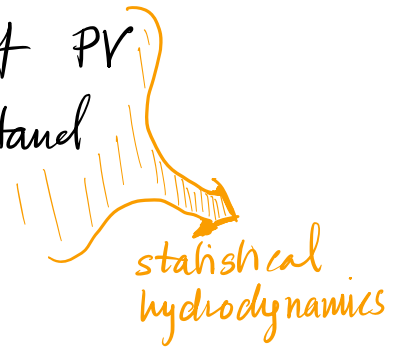
Connection to point-vortices:

$\omega = \sum_{i=1}^N \Gamma_i \delta_{r_i}$ weak solution of (****)

(Helmholtz, Kirchhoff, Gröbli, Poincaré)

L. Onsager's idea (1949)

- (1) "approximate" ω by large number of PV
- (2) apply statistical mechanics to understand long-time behaviour



Predictions

System settles about steady vortex condensates of equal signed PV

PROBLEMS

- (1) Non-regular (weak) $\Rightarrow$ no higher order Casimirs
BUT: conservation of Casimirs affect dynamics
- (2) Numerical simulations contradict steady condensates $\Rightarrow$ "quasi-periodic" behaviour

V. Zeitlin's idea (1991)

Use quantization theory to replace **(****)** by finite dim. Lie-Poisson system

Quantization on a nutshell (ie. $M = S^2$)

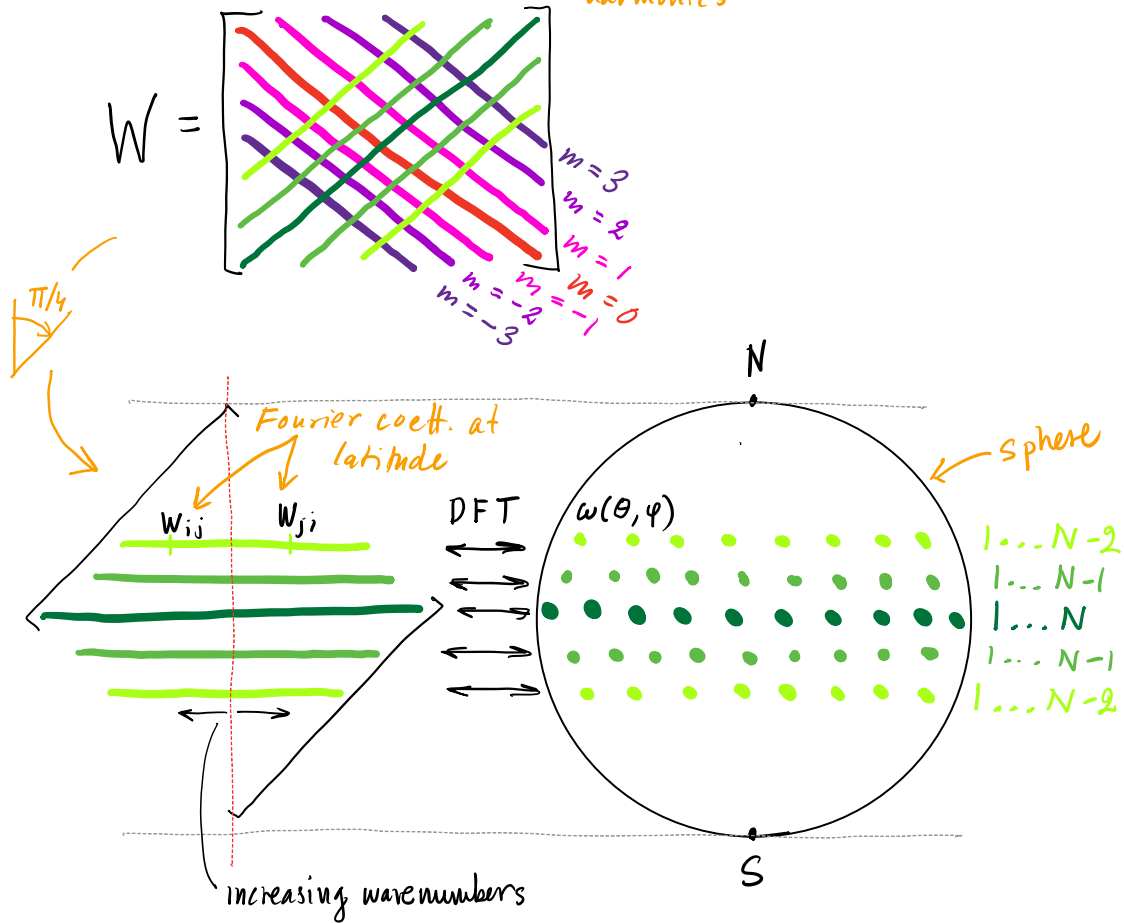
Vorticity state $\omega: S^2 \rightarrow \mathbb{R}$

Aim: mapping $T_N: \omega \mapsto W \in U(N)$ such that

$$T_N(\{\omega_1, \omega_2\}) \approx \frac{1}{\hbar} [T_N \omega_1, T_N \omega_2] \leftarrow \text{matrix commutator}$$

Hoppe (1989): explicit quantization on $\mathbb{T}^2$ and $\mathbb{S}^2$

Route: $\omega \mapsto \sum_{l=0}^{\infty} \sum_{m=-l}^l \omega_{lm} Y_{lm} \mapsto \sum_{l=0}^N \sum_{m=-l}^l \omega_{lm} T_{lm}^N$
 (for $\mathbb{S}^2$) ↑ spherical harmonics $\mathcal{U}(N)$



Euler-Zeitlin equation

$$\omega \in L^\infty(\mathbb{S}^2) \longleftrightarrow W \in \mathcal{U}(N)$$

$$\Delta \psi = \omega \longleftrightarrow \Delta_N P = W$$

$$\Delta_N P = \sum_{i=1}^3 [[P, X_i^N], X_i^N]$$

↑ Hoppe-Yau Laplacian

$$\dot{\omega} = \{\psi, \omega\}$$

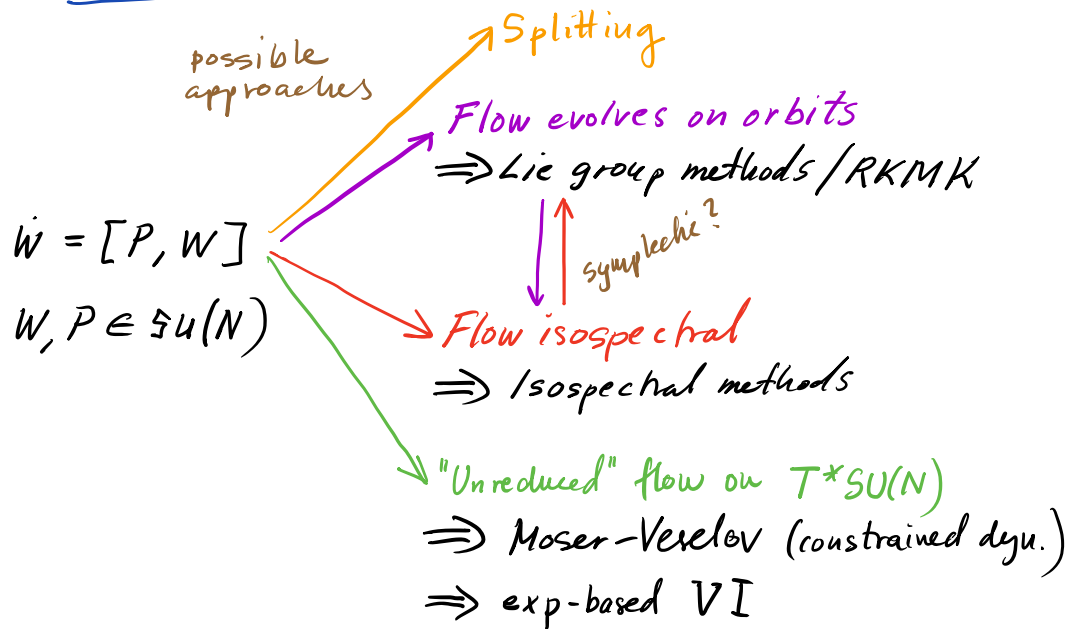
$$\longleftrightarrow \dot{W} = [P, W]$$

Euler-Zeitlin equation

↑ stream matrix

↑ vorticity matrix

Back to numerical integration



PROBLEMS:

exp/dexp/inv :  

non-symplectic :  
 (maybe)

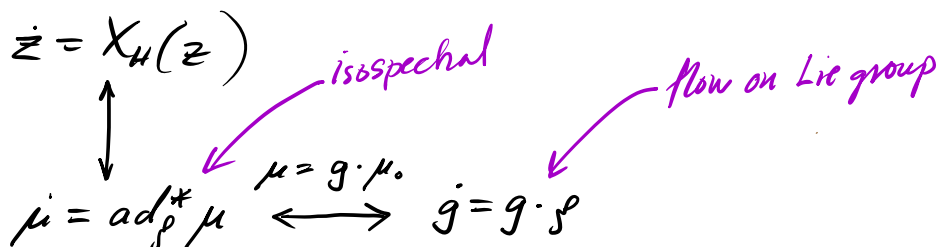
non-parallel : 

Engö & Faloutsos (2001)

The criterion for a good numerical integrator of Lie-Poisson systems becomes the following. The method should produce numerical approximations that stay on the coadjoint orbits, and conserve the Casimirs. Further, the method should either conserve the energy or preserve the Lie-Poisson structure.

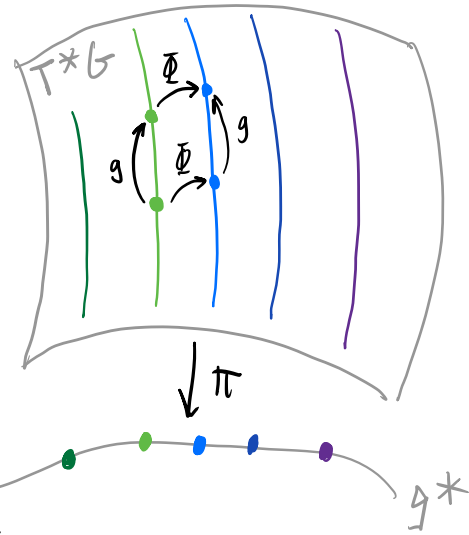
We present methods that automatically retain the two first features. Within this class there exist integrators that also preserve the energy. Conserving the Lie-Poisson structure is a more delicate problem and will not be treated here.

Connection between Lie group methods and isospectral



Discrete reduction theory

$$\begin{array}{ccc}
 T^*G & \xrightarrow{\Phi_{h \circ \pi}} & T^*G \\
 \downarrow \pi & ? & \downarrow \pi \\
 \mathfrak{g}^* & \xrightarrow{\varphi_h} & \mathfrak{g}^*
 \end{array}$$



Theorem: $\mathfrak{g} \subseteq \mathfrak{gl}(N, \mathbb{C})$ quadratic

$\Rightarrow$ every SRK gives LP-integrator on $\mathfrak{g}^*$

$$\begin{array}{c|c}
 c & A \\
 \hline
 & b^T
 \end{array}$$

isospectral

Formula for $\mathfrak{g} = \mathfrak{su}(N)$: $\dot{W} = [B(W), W]$

$$X_i = -h \left(W_n + \sum_{j=1}^s a_{ij} X_j \right) B(\tilde{W}_i)$$

$$K_{ij} = h B(\tilde{W}_i) \left(\sum_{k=1}^s (a_{ik} X_k + a_{jk} K_{ik}) \right) \quad i, j = 1, \dots, s$$

$$\tilde{W}_i = W_n + \sum_{j=1}^s a_{ij} (X_j - X_j^* + K_{ij})$$

$$W_{n+1} = W_n + h \sum_{i=1}^s b_i [B(\tilde{W}_i), \tilde{W}_i]$$

Example (implicit midpoint)

$$W_n = \left(I - \frac{h}{2} B(\tilde{W}) \right) \tilde{W} \left(I + \frac{h}{2} B(\tilde{W}) \right)$$

$$W_{n+1} = \left(I + \frac{h}{2} B(\tilde{W}) \right) \tilde{W} \left(I - \frac{h}{2} B(\tilde{W}) \right)$$

minimal variables: $W_n, \tilde{W}, W_{n+1} \in \mathfrak{su}(N)$